# Homework Set 12: Damped and Driven Harmonic Motion <br> Due Monday, October 16, 2023 

## Problems From TM5.

1) 3-2 Altered: Allow the motion of a 100 g mass attached to a spring with a force constant of $k=10^{4}$ dyne $/ \mathrm{cm}$ initially displaced 3 cm from the equilibrium point and released from rest, to take place in a resisting medium. After oscillating for $10 \mathrm{~T}_{\mathrm{s}}$ ( 10 system periods), the maximum amplitude decreases to half the initial value. Calculate
a) the damping parameter $\beta$, and
b) the frequency $v_{s}$ (compare with the undamped frequency $v_{N}$ (these are $f_{S}$ and $f_{N}$ ).

1 dyne $=1 \mathrm{~g}-\mathrm{cm} / \mathrm{s}^{2}=10^{-5} \mathrm{~N}$ but don't convert! Stay in cgs!

1) 3-11 Derive the expressions (by hand ... show the math) for the energy and energy-loss curves shown in Figure 3-8 for the damped oscillator and reproduce them using your favorite plotting program.
[Make them look like those in the text! MATCH the algebraic expressions from TM5:

$$
\begin{gathered}
E(t)=\frac{m A^{2}}{2} e^{-2 \beta t}\left\{\omega_{N}^{2}+\beta^{2} \cos 2\left(\omega_{S} \dagger-\delta\right)+\beta \sqrt{\omega_{N}^{2}-\beta^{2}} \sin 2\left(\omega_{S} \dagger-\delta\right)\right\} \\
\frac{d E(t)}{d t}=m A^{2} e^{-2 \beta t}\left\{\beta\left(\omega_{S}^{2}-\beta^{2}\right) \cos \left[2\left(\omega_{S} \dagger-\delta\right)\right]-2 \beta^{2} \omega_{S} \sin \left[2\left(\omega_{S} \dagger-\delta\right)\right]-\beta \omega_{N}^{2}\right\}
\end{gathered}
$$

DON'T USE NUMBERED SUBSCRIPTS IN MATHEMATICA! Use $\omega$ Nor $\omega_{0}$ (for the natural frequency) and $\omega$ s for $\omega_{1}$ (for the system frequency ... $\omega$ will be for the driving frequency). The values I used for light damping were $\omega_{\mathrm{N}}=1, \beta$ $=0.1, m=2, A=1$, and $\delta=0$.]
2) 3-16 Discuss the motion of a particle described by equation 3.34 in the event that $b$ < 0 (i.e., the damping is negative).
3) 3-24 For $\beta=0.2 \mathrm{~s}^{-1}$, produce computer plots like those shown in Figure 3-15 for a sinusoidal driven, damped oscillator where $x_{p}(t), x_{c}(t)$, and the sum $x(t)$ are shown. Let $k=1 \mathrm{~kg} / \mathrm{s}^{2}$ and $m=1 \mathrm{~kg}$. Do this for values of $\omega_{0} / \omega_{s}$ of $1 / 9,1 / 3,1.1,3$ and 6 . For the $x_{c}(t)$ solution (Eqn. 3.40), let the phase angle $\delta=0$. And the amplitude $A=-1 \mathrm{~m}$. For the $x_{p}(t)$ solution (Eqn. 3.60), let $F_{0} / \mathrm{m}=1 \mathrm{~m} / \mathrm{s}^{2}$, but calculate $\delta$. What do you observe about the relative amplitudes of the two solutions as $\omega_{0}$ increases? Why does this occur? For $\omega_{D} / \omega_{s}=6$, let $F_{0}=20 \mathrm{~m} / \mathrm{s}^{2}$ for $x_{p}(t)$ and produce the plot again.
You may use any plotting program you are familiar with but you must use a computer. The point is for you to observe how the transient, steady state, and sum functions are affected by the ratio of frequencies. Make sure to explain and label your plots show which curves are the transient, the steady state, and the sum (it's best to use colors). I've plotted them using Mathematica. You may use my file for problem 3-25 (TM5Pr3_25) on $\mathrm{T}: / \mathrm{O}^{\prime}$ Donoghue/Mechanics/Mathematica as a template. Since $3-25$ is critically damped and 3-24 is underdamped, if you use 3-24, make sure you teach it the underdamped $x_{c}(t)$ for 3-24 (kill the kernel if you've been running 3-25)! If you don't, your transient will be incorrect for 3-25.


## Energy and Energy loss by the Damped Harmonic Oscillator TM5 ${ }^{1}$ CHAPTER 3



FIGURE 3-8 The total energy and rate of energy loss for the damped oscillator.

[^0]
[^0]:    ${ }^{1}$ Thornton, T.T. and Marion, J. B., (2004). Classical Dynamics of Particles and Systems. $5^{\text {th }}$ Ed. Belmont, CA: BrooksCole.

