

Remark re: notation

Note that we aren't calling the price V_0 yet. This is because we reserve " V_0 " for the $t=0$ value of the American backward induction algorithm. We have to prove $V_0 = P_0^*$.

Surprising(?) note re: American calls

We'll see in §4.5 that for American calls, $\tau=N$ is always optimal, so there is no early exercise premium. That's why we'll (largely) ignore them.

Prop. Define the adapted process $(V_n)_{0 \leq n \leq N}$ by

$$(i) \quad G_N(\omega) = V_N(\omega)$$

$$(ii) \quad \forall n < N, \quad V_n(\omega) = \max \left\{ G_n(\omega), \frac{1}{1+r} \tilde{\mathbb{E}}_n[V_{n+1}] \right\}$$

Then $V_0 =$ (arbitrage-free) price of the option at $t=0$, and the random variable τ^* defined by

$$\tau^*(\omega) = \min \left\{ n \in \{0, 1, \dots, N\} \mid G_n(\omega) = V_n(\omega) \right\}$$

is an optimal exercise policy.

Rmk

$$\frac{V_n}{(1+r)^n} = \frac{1}{(1+r)^n} \max \left\{ G_n, \frac{1}{1+r} \tilde{\mathbb{E}}_n[V_{n+1}] \right\} \geq \frac{1}{(1+r)^{n+1}} \tilde{\mathbb{E}}_n[V_{n+1}]$$

so $\left(\frac{V_n}{(1+r)^n} \right)_{0 \leq n \leq N}$ is a supermartingale.

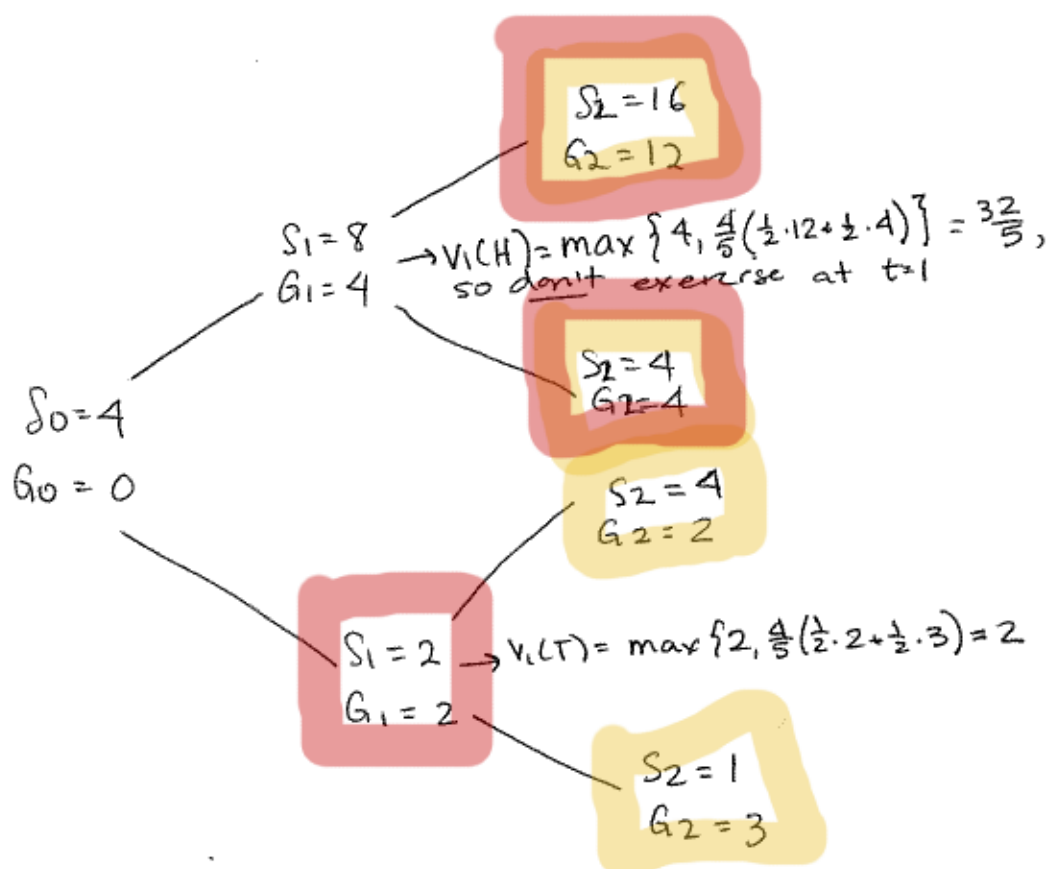
Example: An option with options.

$$N=2, u=2, d=1/2, r=1/4, S_0=4.$$

$$\text{let } M_n(\omega) = \max_{0 \leq k \leq n} S_k(\omega), L_n(\omega) = \min_{0 \leq k \leq n} S_k(\omega).$$

$$\text{let } G_n(\omega) = M_n(\omega) - L_n(\omega).$$

let V be an American lookback option (ω intrinsic values G_n). Find V_0 .



So by proposition on p.53, τ^* defined by

$$\begin{aligned} \tau^*(HH) &= \tau^*(HT) = 2 \\ \tau^*(TH) &= \tau^*(TT) = 1 \end{aligned}$$

is an optimal exercise policy.

But $f^*(\omega) = 2 \forall \omega \in \{H, T\}^2$ is also an optimal exercise policy. (So they needn't be unique.) ■

Example Find all the optimal exercise policies for the American derivative security V which has intrinsic values $G_n = S_n \quad \forall n \in \{0, \dots, N\}$.

Note that $V_N = S_N$, and proceed inductively: assume $V_{n+1} = S_{n+1}$, and compute V_n .

$$\begin{aligned} V_n(\omega_1, \dots, \omega_n) &= \max \left\{ G_n, \frac{1}{1+r} \left(\tilde{P} V_{n+1}(\omega_1, \dots, \omega_n, H) + \tilde{Q} V_{n+1}(\omega_1, \dots, \omega_n, T) \right) \right\} \\ &= \max \left\{ S_n, \frac{1}{1+r} \left(\tilde{P} S_{n+1}(\omega_1, \dots, \omega_n, H) + \tilde{Q} S_{n+1}(\omega_1, \dots, \omega_n, T) \right) \right\} \\ &= \max \{ S_n, S_n \} = S_n(\omega_1, \dots, \omega_n) \end{aligned}$$

So $V_n = S_n$ for all n . This means ANY exercise policy is optimal! In other words,

$$V_0 = S_0 = \tilde{\mathbb{E}} \left[\frac{S_T}{(1+r)^T} \right] = \tilde{\mathbb{E}} \left[\frac{G_T}{(1+r)^T} \right]$$

for all stopping rules τ . ■