

## HOMEWORK SET 05: SEPARATION OF VARIABLES

Due Monday, February 3, 2025

PROBLEMS FROM AOD

1) Show that

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) \psi = \frac{1}{r} \frac{\partial^2}{\partial r^2} (r\psi)$$

PROBLEMS FROM TZDII<sup>1</sup>

8.22) Paraphrased

$$\frac{1}{r} \frac{\partial^2}{\partial r^2} (r\psi) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) \psi + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \psi = -\frac{2M}{\hbar^2} [U(r) - E] \psi \quad (8.49)$$

a) Substitute  $\psi = R\Theta\Phi$ , then multiply by  $r^2 \sin^2 \theta / R\Theta\Phi$  recognizing that partial derivatives only act on a specific variable and functions of any other variable are constants.

b) Keep the functions of  $\phi$  on the left hand side and functions of  $r$  and  $\theta$  on the right hand side. Explain clearly why each side of this equation must be a constant which we will set as  $-m^2$ . Note that the partial derivative becomes a standard derivative in a single-variable equation to derive

$$\frac{d^2}{d\phi^2} \Phi = -m^2 \Phi \quad (8.51)$$

c) From the right hand side above, separate the functions of  $r$  &  $\theta$ . Explain (again) why each side of this equation must be a constant that we will call  $-k$  to derive

$$\frac{1}{\sin \theta} \frac{d}{d\theta} \left( \sin \theta \frac{d\Theta}{d\theta} \right) + \left( k - \frac{m^2}{\sin^2 \theta} \right) \Theta = 0 \quad (8.53)$$

and

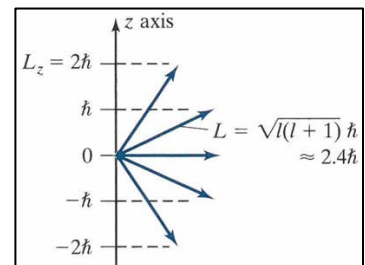
$$\frac{d^2}{dr^2} (rR) = \frac{2M}{\hbar^2} \left[ U(r) + \frac{k\hbar^2}{2mr^2} - E \right] (rR) \quad (8.54)$$

These are the one-dimensional differential equations resulting from the separation of variables that we can solve individually.

8.25) a) Draw a (correctly scaled ... use graph paper and your ruler) vector model diagram similar to Fig 8.14 for angular momentum of magnitude given by  $\ell = 3$ .

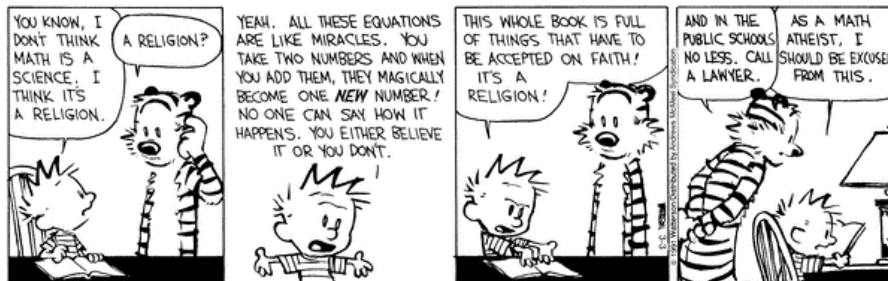
b) How many possible orientations are there?

c) What is the minimum angle between  $\vec{L}$  and the z axis? (USE THE RATIO OF  $L_z / |\vec{L}|$  TO GET AN EXACT ANGLE (USE THE TRIG CHEAT SHEET), DON'T USE YOUR CALCULATOR!)



**FIGURE 8.14**

Classical representation of the quantized values of angular momentum  $\mathbf{L}$  for the case  $l = 2$ . The z component has  $(2l + 1) = 5$  possible values,  $L_z = m\hbar$  with  $m = 2, 1, 0, -1, -2$ . The magnitude of  $\mathbf{L}$  is  $L = \sqrt{l(l+1)}\hbar = \sqrt{2 \times 3}\hbar \approx 2.4\hbar$  in all five cases.



<sup>1</sup> Taylor, Zafiratos, & Dubson, *Modern Physics for Scientists and Engineers*, 2<sup>nd</sup> Edition, Pearson, Prentice Hall, 2004